

Title (en)  
OPTIMIZATION AND CONTROL METHOD FOR A DISTRIBUTED MICRO-GENERATION ENERGY PLANT

Title (de)  
OPTIMIERUNGS- UND STEUERUNGSVERFAHREN FÜR EINE ENERGIEANLAGE MIT VERTEILTER MIKRO-ERZEUGUNG

Title (fr)  
PROCÉDÉ D'OPTIMISATION ET DE COMMANDE POUR UNE INSTALLATION D'ÉNERGIE À MICRO-GÉNÉRATION RÉPARTIE

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Application  
**EP 15159163 A 20150316**

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Abstract (en)  
A control method of a plant for the micro-generation of distributed energy is disclosed, wherein the plant is installed in a local unit, is connected to an electric network of an external supplier and comprises at least generation resources comprising of generators of electric and thermal energy, among which at least a co-generator in the form of fuel cell and photovoltaic panels, and energy storage resources, among which at least an electric battery and a thermal accumulator (boiler), wherein the following steps are provided: acquiring status variables comprising at least an adjustment of said fuel cell (  $M(k)$  ), a loading status of said battery (  $S(k)$  ) and a status (  $H(k)$  ) of said thermal accumulator, chasing a time sequence (  $k=1, \dots, N$  ) of reference values comprising at least, from an electric production from photovoltaic panels (  $P_{FV}(k)$  ), an electric load (  $L_{EL}(k)$  ) and a thermal load (  $L_{TH}(k)$  ) demanded by a user, through a predictive model defined for minimising a cost function which includes a total electric power (  $P_{EL}(k)$  ) and a total thermal power (  $P_{TH}(k)$  ) produced by said generators of electric and thermal energy, so as to obtain a sequence of optimised variables, comprising at least adjustment/modulation of said fuel cell (  $M_{REF}$  ), power delivered by said thermal accumulator (  $P_H(k)$  ) and a slack variable (  $\mu(k)$  ) to be used as input variables for said fuel cell and said electric battery and wherein said status variables (  $M(k)$  ,  $S(k)$  ,  $H(k)$  ) are put in relationship with the relative input variables (  $M_{REF}(k)$  ,  $P_{BATT}(k)$  ) through discrete-time dynamic models defined as:  $M_{k+1} = e^{-T_s/\tilde{A}} M_k + 1 - e^{-T_s/\tilde{A}} M_{REF,k}$  ;  $S_{k+1} = S_k - k_s T_s P_{BATT,k}$  ;  $H_{k+1} = e^{-T_s/H} H_k + k_H (1 - e^{-T_s/H}) P_H,k$  where  $T_s$  is a sampling time,  $\tilde{A}$  is a time constant of said fuel cell,  $k_s$  is a parameter of the loading and unloading dynamics of said electric battery,  $k_H$  and  $H$  are parameters of the dynamics of said thermal accumulator.

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Citation (applicant)  
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