Test Case: Power System Voltage Stability

Mats Larsson









Preview

- The People from ABB
- Characteristics of Power Systems
- Voltage Stability
- Corrective Measures
- The ABB Platform for Corrective Control
- What do we need from CC?
- The ABB Power Grid Test Case
- Conclusion

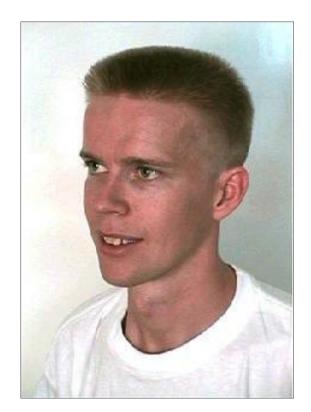
People Involved From ABB

Eduardo Gallestey



- PhD in Mathemathics 1998
 - University of Bremen
 - Optimal and robust control, optimization etc.

Mats Larsson



- PhD Industrial Automation 2001
 - Lund University
 - Control and stability of power systems

Characteristics of Power Systems



- Large-scale
- Substantial nonlinearity
- Wide span of time-scales
- Uncertainty
- Changing operating point
- Mix of continuous and discrete control variables
- Embedded Controllers
- System model has differentialalgebraic structure
- A good example of a "complex" system!

Control of Power Systems

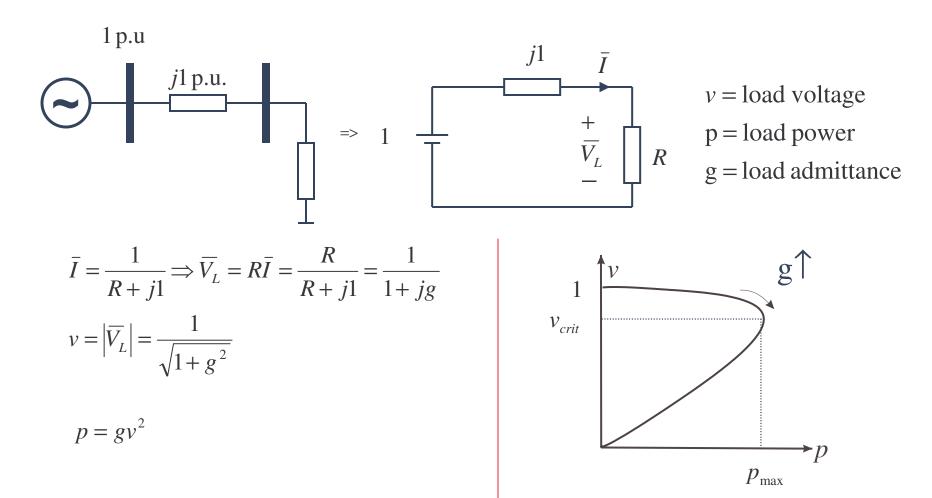
- Global control problem extremely difficult
- Decomposition, Controller hierarchies

- Some stability concerns in PS
 - Frequency stability Simple linear decentralized control
 - > Transient stability -- Energy functions, Lyapunov
 - Small-disturbance stability Linear analysis, H_inf_etc.
 - Voltage stability Model Predictive Control etc.

System collapse due to Voltage Instability

Date	Location	Time to Collapse
860413	Winnipeg, Canada, Nelson River HVDC link	1 s
861130	SE Brazil, Paraguay, Itaipu HVDC link	2 s
850517	S Florida, USA	4 s
870822	W Tennessee, USA	10 s
960702	Western USA	35 s
831227	Sweden	55 s
820902	Florida, USA	1-3 min
821126	Florida, USA	1-3 min
821228	Florida, USA	1-3 min
821230	Florida, USA	1-3 min
770922	Jacksonville, Florida	minutes
820804	Belgium	4-5 min
870112	Western France	6-7 min
651209	Bretagne, France	minutes
761110	Bretagne, France	minutes
870723	Tokyo, Japan	20 min
781219	France	26 min
700822	Japan	30 min

Voltage Stability



Maximum transfer: $p = p_{max}$ at $v = v_{crit}$

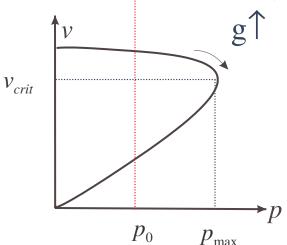
Stability analyis

Load constant power behavior:

$$\begin{cases} T \frac{dg}{dt} = p_0 - gv^2 & \text{(increase } g \text{ if consumption too low)} => f(g) = \frac{dg}{dt} = \frac{1}{T} (p_0 - \frac{g}{1 + g^2}) \\ v = \frac{1}{\sqrt{1 + g^2}} \end{cases}$$

➤ Stationary points given by:

$$f(g) = 0 \Rightarrow g^* = \frac{1}{2p_0} \pm \sqrt{\frac{1}{4p_0^2} - 1}$$



 $p_0 < 0.5$ - two equilibrium points

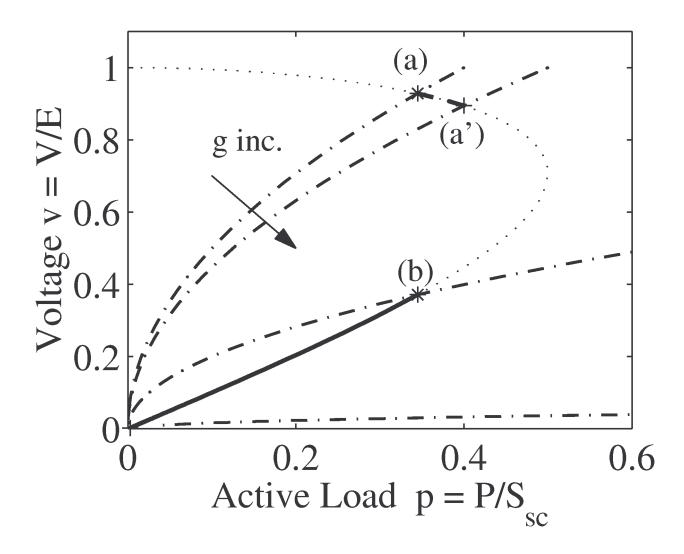
 $p_0 = 0.5$ - the two equilibrium points coalesce

 $p_0 > 0.5$ - no equilibrium points

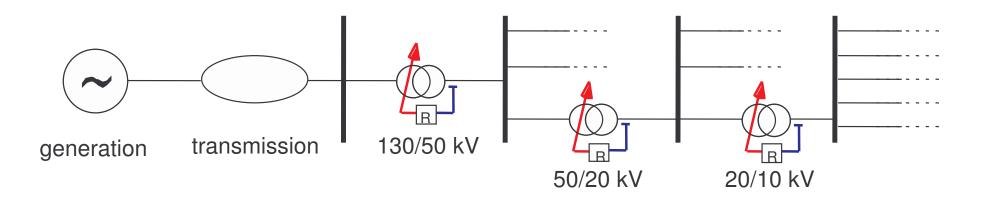
Unstable if: $p_0 > p_{\text{max}} \text{ or } v < v_{crit}$

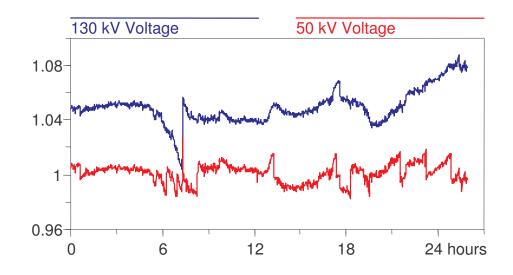
Simulation Results

Small Step in p0 (a) – stable case, (b) unstable case



Tap Changer Control

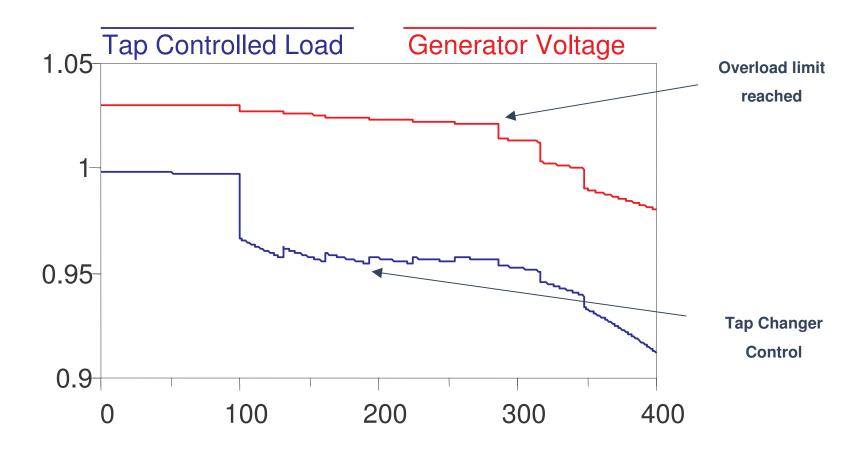




- Used to control customer voltage
- Relay control
- Time delay + Deadband
- Uses a local viewpoint
- Bad for System Stability!

Generator Overload Limits

- Generators normally under terminal voltage control
- If the generator is overloaded, voltage control is lost

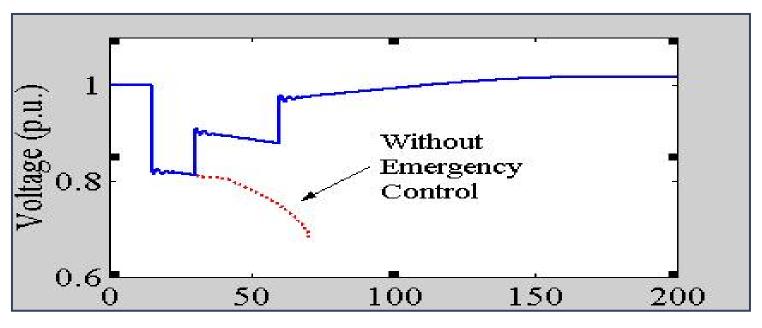


Typical Instability Scenario

- 1. Line or generator outage reduces the voltage in an area
- 2. Temporary load reduction
- 3. Transfer capacity to the area is reduced
- Load demand recovers (distribution voltage control, inherent dynamics)
- 5. Voltage is further reduced
- 6. Generator overload protection activated
- 7. Collapse!

Time scale: seconds to several minutes

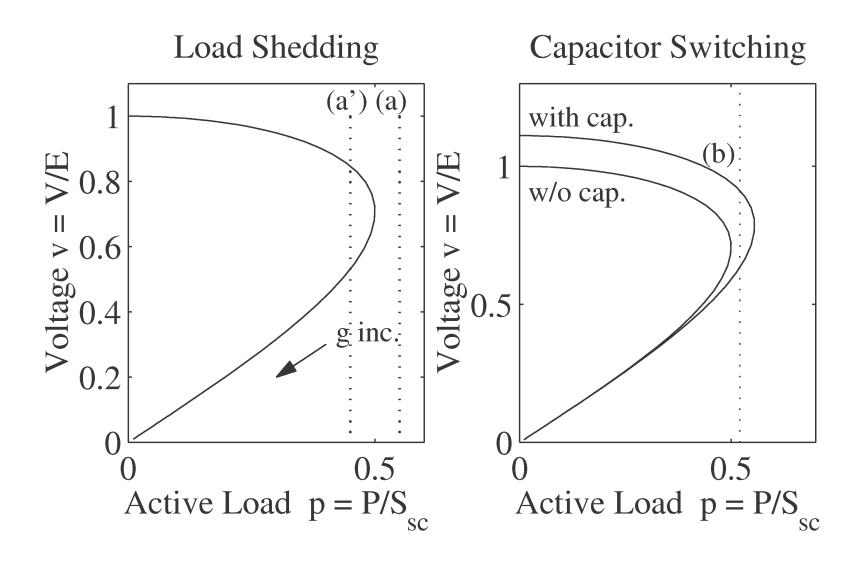
Countermeasures against Voltage Instability



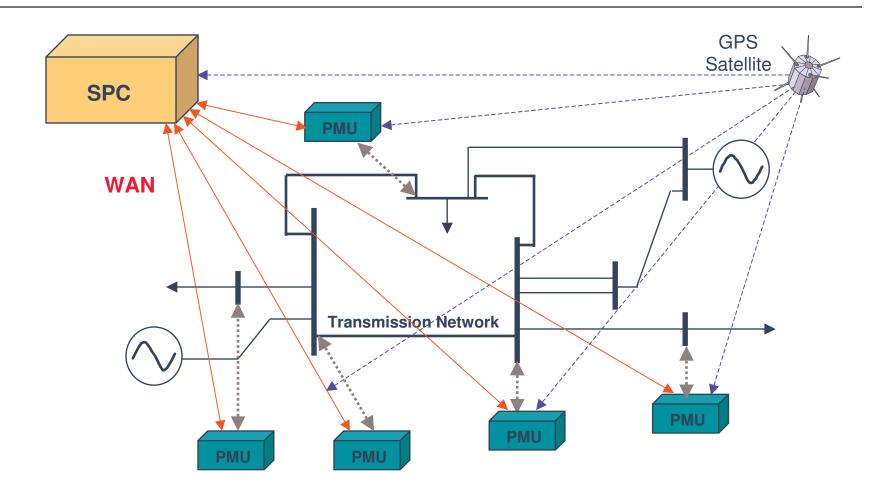
Time (seconds)

- Load shedding
- > Tap locking
- Capacitor switching
- Generator voltage setpoints

Countermeasures (ctd.)

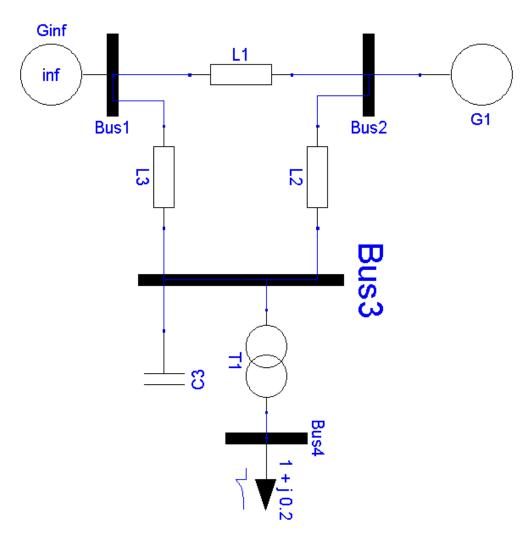


Wide-area Protection



- Snapshot of power system topology and state every 50-250 ms
- Sophisticated control possible

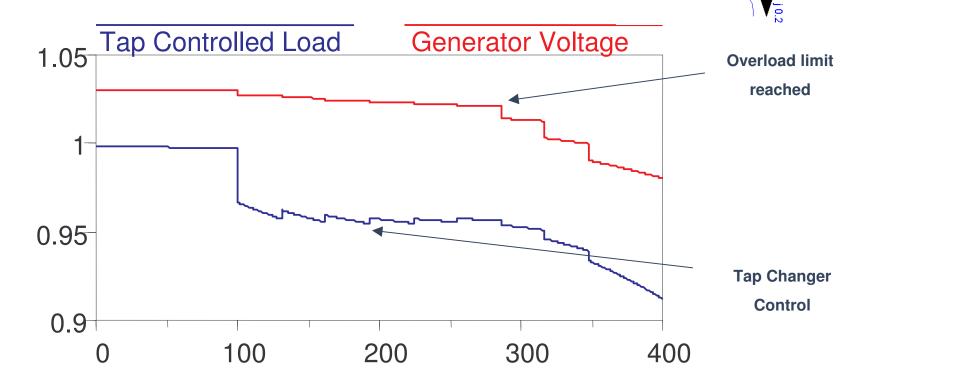
The ABB Power Grid Test Case



- Small-scale example
- Discrete Step Controls
 - > Tap locking
 - Load Shedding
 - Capacitor Switching
- Hybrid Behaviour
 - Generator overload protection
 - Transformer Relay Control

Collapse Scenario

- Line tripping (L3) after 100 s
 - Inherent Load Recovery
 - ➤ Tap Changer Tries to Restore Voltage
 - Generator field limit activated at 286 s
 - Collapse



What Do We Need from CC?

- Optimal Control Problem
 - > Find optimal switching sequences for our controls
- Observability Analysis
 - > Select a *minimum but sufficient* number of measurement points
- Controllability
 - > Select a minimum but sufficient number of control points
- Reachability Analysis
 - Which are the safe operating regions?
 - When is the last time to stabilize the system, given some set of available controls?
- and other things ?

Conclusion

- Industrially highly relevant problem
- We are dealing with transmission not distribution
- A challenging test case:
 - Nonlinearity
 - Load behaviour is uncertain
 - Hybrid behaviour
 - **■** Embedded relay controls
 - **■** Limiter logic
 - Large Scale
- Present Status
 - > Now available in Modelica language, SIMULINK SimStruc
 - > T. Geyer at ETH currently works on a PWA model
- Later on, medium and large scale examples will be available